Technical Description

GPS Satellite Controlled Clock 6875



Version 03.01 22.02.2007



Safety information

The safety regulations and technical data are important for the smooth running of the devices and the protection of people and equipment. Strict compliance with these regulations is required. In case of non-compliance with these regulations the guarantee and warranty claims for the device expire. There is no liability for possible consequential damages.

Safety of the Devices

The production of this device follows the latest technological standards and safety regulations.

The device must not be assembled by anyone but trained personnel. Please make sure that all the connected cables are laid and fixed properly. The device is to be run with the supply voltage stated on the identification plate only.

Only trained personnel or specialists may operate the device.

Repair on opened devices must not be carried out by anyone but specially trained staff or by the **hopf** Elektronik GmbH company.

If the maintenance work requires the opening of a device or if a fuse needs changing the device must be separated from all voltage supplies.

If there are reasons to believe that the operational safety can no longer be guaranteed the device must be taken out of service and labelled accordingly. The safety may be impaired when the device does not operate properly or if it is obviously damaged.

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1 General information

The 6875 radio-controlled clock is a universal GPS reception module with a highly accurate time reference developed for controlling industrial processes. The 6875 snap-in module for 35mm (DIN) track mounting is fitted with three **PhotoMOS signal relays**, an analogue and digital TTL output and up to four independent serial interfaces.

The PhotoMOS signal relay outputs can be used, for example, for the SPS or measuring process control. Following output modes are available:

- DCF77 pulse
- System status (radio-controlled or quartz)
- Status of the power supply on/off
- Cyclical pulses
- Non-cyclical pulses (1 pulse per day at a defined time, 1 pulse per year at a defined time and on a defined date)

The analogue output can be used to synchronize DCF77 or IRIG-B systems.

The serial interfaces **COM0...COM3** are used for the output of different pulses and data strings. Each interface can be configured with *hopf* remote software.

The 6875 snap-in module has further features:

- · Potential-free antenna circuit
- All outputs potential-free
- All settings can be parametered via the COM0 serial interface
- COM1 interface can be switched from RS232 to RS422 via configuration software
- switchable analogue output IRIG-B / DCF77

The following versions of the system are available (indicated on the identification label):

- FG6875G00 (GPS 6875 snap-in module basic version) with
 - 3 PhotoMOS pulse outputs
 - serial interface COM0: RS232
 - serial interface COM1: RS232/RS422
 - simulation output for DCF77 antenna simulation or IRIG-B 12x (x=0..3)
 - · programming cable, remote software and technical documentation included
- FG6875G01 (6875 snap-in module) with
 - GPS 6875 snap-in module basic version FG6875G00
 - · Serial interface COM2: optical output
- FG6875G02 (6875 snap-in module) with
 - GPS 6875 snap-in module basic version FG6875G00
 - Serial interface COM2: optical output
 - Serial interface COM3: optical output
- FG6875G03 (6875 snap-in module) with
 - GPS 6875 snap-in module basic version 6875
 - Serial interface COM2: optical output
 - Serial interface COM2: optical input

The configuration software on the CD supplied is available for the most common MS Windows, Linux and Sun Solaris operating systems (for more details see 4.1).



2 Quick installation

Synchronization is accelerated by initialising the GPS 6875 satellite clock when first putting into operation. It is not absolutely necessary to enter set-up values. However, without initialisation it may be several hours before the first signals are received.

For quick installation it is necessary to set the following set-up values in the GPS 6875 satellite controlled clock:

- · Earth the device
- · Connect the antenna
- Create communication between the PC and the remote-controlled clock
- · Connect the power supply
- · Install and start the remote software
- Set the current local time
- Ser the local time difference to UTC (local time UTC)
- · Set changeover dates
- Set the position data of the location; if this is not known then set an approximate value or set everything to zero
- · Activate the reset of the clock after the next minute change
- Wait approx. 10 minutes to 4 hours before synchronizing the radio-controlled clock

The individual menu items of the programme are explained on the following pages.



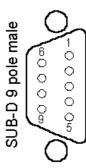
3 Hardware

3.1 Front panel components



Connector X1	2 x 4 pole plug-in connectors (female) with codeable profile and threaded flange (corresponding connector (male) is included)
+Vin –Vin	Connection for positive potential of the power supply Connection for negative potential of the power supply
+OC3, +OC2, +OC1 -OC3, -OC2, -OC1	PhotoMOS signal relay connection for positive voltage potential (Drain) PhotoMOS signal relay connection for negative voltage potential (Source)

Connector X2	9 pole SUB-D connector				
Pin No.:	Function				
1, 5	GND				
4	Digital output, TTL				
	COM0	RS232			
2	Receiving line	(RxD0)			
3	Transmission line	(TxD0)			
	COM1	RS232	RS422		
6	Transmission line	TxD1	$+TxD1^{1}$		
7	Transmission line		$-TxD1^2$		
8	Receiving line	RxD1	-RxD1 ²		
9	Receiving line		+RxD1 ¹		



high active low active



LED / Key	Function
CLK	green, indicates the synchronization status of the clock
C1-C3	yellow , indicates the switch status of the corresponding PhotoMOS signal relay
DEF key	(DEF)ault key for restoring the standard configuration
BNC connec-	
tors	
IRIG-B /	analogue output for the output of the modulated IRIG-B or DCF77 signal
DCF77-Out	(BNC female connector)
GPS-In	input for GPS antenna (BNC connector)
	1
Option	optical interfaces COM2, COM3 (ST connection: bayonet)
FL 1	optical transmitter for serial interface COM2
FL 2	optical transmitter COM3 / optical receiver for serial interface COM2

3.2 Installation

3.2.1 Power supply

The power supply is connected via the 2 x 4-pole connectors, as supplied, with threaded flange, connections **+Vin** und **-Vin** on the connecting unit X1. The system is provided with a voltage of **18...72 VDC**..

The internal voltage supply of the 6875 snap-in module is potential-free. It must be earthed on the rear side of the housing via the screw as labelled, in order to compensate the potential difference between the ground potential of the housing and the earth.

Please Note:	ALTHOUGH THERE IS INTERNAL PROTECTION AGAINST WRONG POLING, ATTENTION
	MUST BE PAID TO THE CORRECT VOTLAGE AND POLARITY WHEN CONNECTING THE
	POWER. ONLY QUALIFIED STAFF SHOULD FIRST PUT THE EQUIPMENT INTO OPERA-
	TION.

3.2.2 Connecting the antenna

The antenna is connected via the **hopf** antenna cable to the **GPS-In** BNC connector (more information in the GPS appendix).

3.2.3 Installation of the configuration software

see 4.2.



3.3 Technical Data

General

Snap-in module dimensions of

housing

max. outer dimensions

width: 65 mm, height: 105 mm, depth: 130 mm

width: 65 mm, height: 105 mm, depth: 155 mm

Power supply min. 18 to max. 72 VDC

Output isolation 500V DC typical / max. performance 3,5 VA / 4 VA

Temperature range 0...+ 50 °C with improved free wheeling characteristics

0...+ 70 °C with restricted free wheeling characteristics

MTBF > 295.000 hrs.

Accuracy (GPS Model)

PPS pulse (internal) ± 300 nsec

VCO control (internal time base) ± 0,1 ppm, after approx. ½ hr. continuous GPS recep-

tion

Free wheeling characteristics ± 0,05 ppm, after VCO control at a constant tempera-

ture +10...+50 °C

PPS drift depending on changes in power supply in free wheeling

status

± 0,0002 ppm/V

PPS drift depending on changes in temperature in free wheeling

status

± 0,16 ppm/°C, at constant Uin=24V and temperature

radient of approx. 1,5°C/min

Accuracy (quartz model)

Free wheeling characteristics ± 0,5 ppm, after factory setting of VCO control at a con-

stant temperature of +20°C

Accuracy of backup clock ± 25 ppm from +10°C to +50°C

Backup clock max. 3 days

Optical coupler

max. performance, capacity in

Ohms

60V DC / 200 mA

Switch on/off delay 130 / 70 µsec. at 10 mA switch mode power supply

Output isolation 500V DC

DCF77 pulse output at COM1,COM2 (FL 1),

COM3 (FL 2), TTL (X2)

accuracy same as internal PPS pulse signal level depending on output interface

DCF77 simulation output output at BNC (IRIG-B / DCF77-Out)

accuracy same as internal PPS pulse

carrier signal frequency $77.5 \text{ kHz} \pm 25 \text{ ppm}$ signal level $3...5 \text{ mV}_{pp}$ at 50 Ohm



IRIG-B pulse output at COM1,COM2 (FL 1), (digital / IRIG-B00x) COM3 (FL 2), TTL (X2) same as internal PPS pulse signal level depending on output interface

IRIG-B analog (IRIG B12x) output at BNC (IRIG-B / DCF77-Out)

accuracy same as internal PPS pulse

carrier signal jitter (1kHz) ± 2 µsec

signal level ca. 2 V_{pp} (± 10%) at 50 Ohm

ca. 2 V_{pp} (± 10%) at 600 Ohm

modulation ratio 3:

Interfaces: COM0, COM1 asynchronous, without handshake

Baud rate 300 - 19.200 Baud

Stop bit 1 / 2 bit Word length 7 / 8 bit

Parity no, even or odd

Line length The line lengths depend on the type of line and the

setting of the Baud rate.

Option: optical interface, $\lambda = 820 \text{ nm}$

Interfaces: COM2, COM3 asynchronous, without handshake, optical

Baud rate 300 - 19.200 Baud

Stop bit 1 / 2 bit Word length 7 / 8 bit

Parity no, even or odd

Optical transmitter: Connection: ST series (bayonet)

COM2 (FL 1), COM3 (FL 2) Optical receiver: COM2 (FL 1)

Wave length $\lambda = 820 \text{ nm}$

Cable types supported (multi- $50/125 \mu m$, $62.5/125 \mu m$, $100/140 \mu m$ or

mode) 200 µm HCS ® fibre

GPS receiver 8 canal, C/A Code, code plus carrier tracking

Log-in sensitivity -134 dBm Log-out sensitivity -143 dBm

Frequency range L1 = 1575,42 MHz

Recording time

Warm start < 1 min. (backup max. 3 days)

Cold start 30 min. - 4 hrs.

(1st installation without definition of position)

Accuracy \pm 300 nsec Temperature range 0...+ 60 °C

Additional components: see GPS accessories

Please Note: SUBJECT TO ERRORS AND TECHNICAL MODIFICATIONS



4 Software

4.1 System requirements

The **hopf** 6875 configuration software is for configuration of a **hopf** 6875 radio-controlled clock via a serial interface. The serial interface cable included is connected between the computer (at the free serial interface) and the radio-controlled clock (**COM0**).

Depending on the platform the following system requirements are necessary for the remote software and/or the installation programme:

Windows

- Windows 95, 98, ME, NT, 2000, XP
- min. 32 MB RAM (128 MB recommended)
- min. 40 MB free hard disk memory
- screen resolution min. 640x480 (1024x768 recommended)

Linux

- RedHat 7.1, SuSE 7.2 or Debian 2.2R3
- glibc 2.x
- libstdc++-libc6.1-1.so.2
- X-Windows
- min. 32 MB RAM (128 MB recommended)
- min. 110 MB free hard disk memory
- screen resolution min. 640x480 (1024x768 recommended)

Solaris SPARC

- Solaris 8
- X-Windows
- min. 32 MB RAM (128 MB recommended)
- min. 75 MB free hard disk memory
- screen resolution min. 640x480 (1024x768 recommended)

Solaris x86

- Solaris (x86) 8
- X-Windows
- min. 32 MB RAM (128 MB recommended)
- min. 75 MB free hard disk memory
- screen resolution min. 640x480 (1024x768 recommended)

Please Note:

FOR PROBLEM-FREE EXECUTION THE INSTALLER AND/OR THE CONFIGURATION SOFTWARE REQUIRE ADMINISTRATOR OR ROOT RIGHTS FOR THE CORRESPONDING INTERFACE DEVICE.



4.2 Installation of the remote software

To install the remote software the installation programme/script must be started. This requires a graphic user interface:

Windows

6875_v01_03_Win32_install.exe

Linux

6875 v01 03 Linux install.bin

Solaris SPARC

6875_v01_03_Solaris_SPARC_install.bin

Solaris x86

6875_v01_03_Solaris_x86_install.bin

Follow the instructions in the installation programme to complete the installation.

4.2.1 Uninstalling the remote software

Windows

The application can be uninstalled via system control:

- Start menu ⇒ Set-up ⇒ System control ⇒ Select software
- Select remote software and click add/remove

 □ Uninstall-programme starts
- Follow the instructions in the uninstall-programme

Unix Platforms

The application can be removed via the uninstall-programme supplied (Uninstall6875) which is found in the corresponding subdirectory UninstallerData (e.g. /opt/Hopf/6875/UninstallerData/Uninstall6875).

4.2.2 Start programme

Windows

After installation has been completed in the chosen directory (e.g. C:\rogramme\Hopf\6875) the configuration software can be started by selecting the appropriate link (e.g. Start ⇒ Programme ⇒ Hopf ⇒ Hopf 6875).

Unix Platforms

After completing installation into the chosen directory (e.g. /opt/Hopf/6875) the configuration software can be started via Startscript (Hopf6875) which can be found in the bin-directory (e.g. /opt/Hopf/6875/bin/Hopf6875).

Please Note: SINCE THE VALUES SHOWN ARE CONSTANTLY UPDATED, DELAYED REACTION TIMES IN THE INPUT FIELDS WITH MOUSE OR KEYBOARD ENTRIES ARE POSSIBLE WITH LESS POWERFUL SYSTEMS.



4.2.3 Trouble shooting

- If there is an initialisation error when the configuration software is started then the serial interface is either incorrectly configured or is being used by another programme.
- If a communication error arises during the execution of the configuration software, then
 the radio- controlled clock is incorrectly connected or another instrument is connected to
 the interface selected.
- If another programme is using the same serial interface as the configuration software (e.g. an NTP service), then this must be ended to ensure that the configuration software functions correctly.
- If the monitor resolution is low or some fonts are missing there may be slight distortion in the script of the configuration software. This does not however affect the functions.
- If during installation a JAVA VM version is selected which is already installed, then care
 must be taken that the minimum version is Java2 1.3. Usually we advise using or installing JAVA-Runtime as supplied.
- Information about possible errors specific to operating systems can be found in the corresponding readme-file as supplied.

If there are any questions or installation problems please contact the support team at Ruprecht & Partner OEG under the e-mail address: support-hopf@rdcs.at

Updated versions can be found on the website of Ruprecht & Partner OEG: http://www.rdcs.at/



4.3 Functions of the configuration software

4.3.1 General

The **hopf** 6875 configuration software is for convenient configuration of a **hopf** 6875 radio-controlled clock via an RS232 interface. All the parameters of the radio-controlled clock can be displayed or set via a graphic user interface. These are divided into categories (e.g. time zone, changeover time, serial parameters, etc.). Each of these categories is illustrated on a tab in the upper section of the window.

A click of the mouse activates a tab – the window with the corresponding details is switched up. This is divided into two areas: the current values and the values to be set. When a tab is selected, the current values of the radio-controlled clock are requested and displayed. In this case the values to be set correspond to the current values and can be changed by clicking the corresponding arrow fields or by manual input.

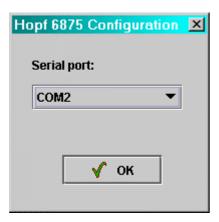
Activating the button "SEND" transmits the values to be set to the radio-controlled clock. If an error occurs a message is emitted, otherwise the current values are updated.

The software can be ended by activating the button "END".

4.3.2 Selecting the serial interface

The serial interface to which the radio-controlled clock is connected can only be selected when the programme is started.

Depending on the PC or operating system it may take some time to set up the selection window.



After selecting the appropriate interface the **hopf** 6875 configuration software will try to connect to the radio-controlled clock. If no connection can be made a corresponding message will appear. In this case please check that the cable is correct and/or that the cable is connected to the correct interfaces.

A new attempt to make a connection on the same interface can be made by selecting any other tab. If this is to be tried on another interface then the programme must be ended and re-started.

4.3.3 Changing the language

The language used in the software can be changed during operation by selecting the desired language in the selection menu on the left hand side of the window. This takes effect immediately after closing the selection window (perhaps with a slight delay, depending on the type of PC).



4.3.4 Information

In this section information about the software or contacts can be found in the info dialogue which is activated by clicking on the info button (on the right next to the button "help").



4.3.5 Extras

This section makes it possible to save a complete configuration of a radio-controlled clock in a configuration file (text file) or to load down from a configuration file and transmit to the radio-controlled clock.





SAVE (IN A FILE)

Selecting the button "SAVE" opens a dialogue which enables selection of a target directory or indication of a file name. After the target directory or a file name has been defined the current configuration of the radio-controlled clock can be saved by selecting the button "SAVE". As soon as "SAVE" has finished, a confirmation dialogue appears which reports either success or error.

LAODING (FROM A FILE)

If a configuration is to be loaded which is already available or has already been saved then the button "LOAD" should be clicked. A dialogue appears in which the file to be loaded is selected. After selecting the file and confirming this with the button "OPEN" the following dialogue appears:

[LOAD DIALOGUE]

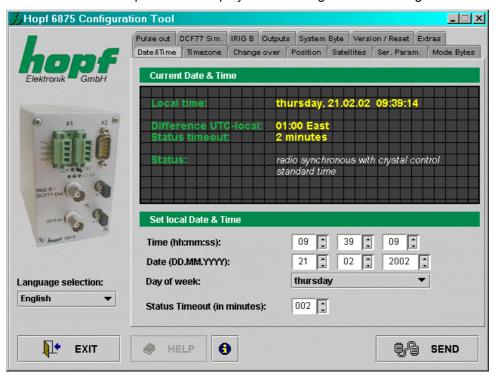
This dialogue shows in a well-structured form all the configuration data in the file which has been loaded. The left column contains the definition of the value, the middle column the actual value and the right column the status. If the status is "OK" (green), then this value is available – if not, then the status of this value is "ERROR" (red). If at least one value has the status "ERROR", the configuration cannot be transmitted to the radio-controlled clock. Otherwise the configuration shown can be transmitted to the radio-controlled clock by activating the button "SEND". This procedure can take some time and is confirmed after completion with a success or error message. The dialogue can be ended by selecting the button "CLOSE":

The button **"HELP"** is for activating online help – this contains all the information contained in this document and additional general information about GPS.



4.3.6 Date & Time

This section makes it possible to display and/or change values relating to date and time.



The following values are displayed or can be configured:

Day of the week, date, time:

Setting the day of the week, the date and the time is only necessary when commissioning the radio-controlled clock. In this case the configuration software checks the plausibility of the time and date values entered. Before transmission of the time to the radio-controlled clock the correct day of the week for the date entered is checked – if the day of the week entered differs from that which is calculated then a corresponding message will appear.

Time difference:

Shows the actual time difference between local time and UTC in hours and minutes.

In this section the value is for information purposes only and can only be changed in the section "Time Zone" (4.3.7).

Status Timeout:

Shows the time delay in minutes until the resetting of the radio-controlled bit in the time status. This value can be between 2 and 255 minutes.



Status:

Is made up of: synchronization status (e.g. quartz mode, radio-controlled mode, etc.) and actual time status (e.g. daylight saving, standard time, announcement of changeover etc.). It is for information purposes only and cannot be changed.

Synchronization status of the radio-controlled clock:

- invalid time of day
- quartz mode
- radio-controlled mode (without quartz frequency control)
- radio-controlled mode (with high accuracy / with quartz frequency control)

Time status for local time of day:

- standard time
- · daylight saving time
- · announcement of changeover
- · announcement of leap second

4.3.7 Time Zone

In this section the time zone for the location of the radio-controlled clock can be displayed and adjusted. Setting the time difference is only necessary when commissioning.



The time difference (country- or location- specific time offset to UTC, difference between local time and UTC) is made up of the following information:

Hour, minute and the information as to whether the location is west or east of the 0 meridian (Greenwich).

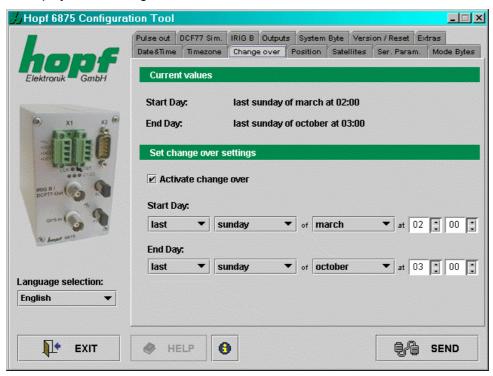
The configuration software checks the plausibility of the values entered.

Example: West (-) 08:00 USA and Canada (Pacific Time)
East (+) 01:00 Germany



4.3.8 Changeover time/changeover point

In this section the daylight saving/standard and standard/daylight saving changeover times can be displayed and changed.



In order to set the changeover times the changeover function must first be activated. If no changeover is required this must be deactivated \Rightarrow time of day (local time) then runs in standard time status.

To set the changeover times the following information is required:

- first, second, third, fourth or last day of the week in the month
- day of the week
- month
- time in hours and minutes



4.3.9 Position

This section enables the display and setting of the geographical position of the radio-controlled clock.



Setting the approximate location position (if known) shortens the time required for first initialisation of the GPS receiver in the radio-controlled clock.

The entries of latitude and longitude are in degrees, minutes, 1/100 und 1/10000 minutes and the following additional information concerning the geographical location:

Entry for latitude:

North = northern hemisphere

South = southern hemisphere *Example:* **North 51°12,3651**

Entry for longitude:

East = east of Greenwich meridian

West = west of Greenwich meridian Example: East 007°37,8426

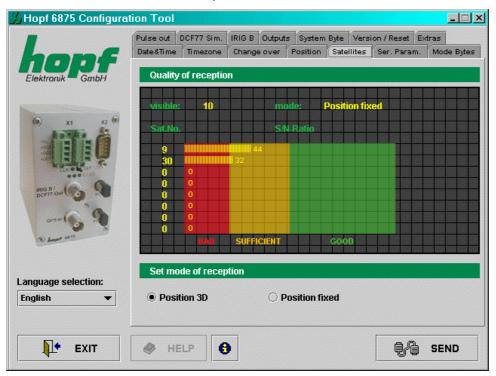
For accelerated synchronization the GPS radio-controlled clock requires only the entry of the approximate location. For the exact position shown in the above example the following entry would suffice:

North 50°00,0000 East 007°00,0000



4.3.10 Satellites

This section enables display of the current satellite receiver quality as well as setting of the evaluation mode for GPS satellite reception.



In the display for GPS satellite reception quality the following values are shown:

- number of satellites visible at the given time
- evaluation mode for GPS satellite reception
- reception quality as **S/N Ratio** (signal to noise ratio) for individual satellites

The data shown are updated periodically.

The evaluation mode for the GPS satellite reception can be set to 3D or Position fixed.

The accuracy of the time evaluation is determined by the exact calculation of the position of implementation of the clock. For this calculation reception from at least 4 satellites is necessary (3D evaluation mode). With the calculated position the signal transmission times to several satellites are determined and from their mean value the exact second mark is created. In 3D evaluation mode the second mark has an accuracy of \pm 1 μ sec.

In many cases it is sufficient with stationary installations to have a restricted evaluation of the second mark e.g. up to several milliseconds. In the **Position fixed** operating mode the accuracy depends largely on the exact entry of the location of implementation. Then the calculation of the second mark is already calculated with one satellite and the position given. When entering the position up to \pm 1 minute, the accuracy of the second mark is already better than \pm 20 μ sec. With an even more exact entry it is even possible to achieve a value of \pm 1 μ sec.

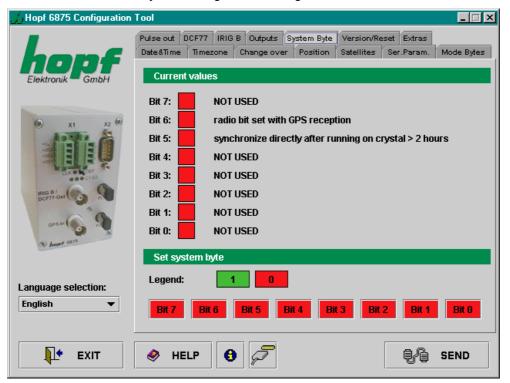


Position fixed has the advantage that the GPS radio-controlled clock can be synchronized with one satellite only. The antenna can also be installed in locations where less than a quarter of the sky is visible. In many cases it is possible to mount the antenna indoors near the window (short cable lengths, no lightning protection).

If, in this mode, 4 satellites are available the evaluation jumps automatically to 3D evaluation mode and calculates the exact position. In this way the accuracy with a single satellite increases to \pm 5 μ sec.

4.3.11 System Byte

This section permits the configuration of additional internal system functions. These are activated and deactivated by the setting and resetting of a bit.





Each bit has two possible statuses: **IN (1)** and **OUT (0)**. **Default** system byte configuration: Bit No.: 0 ... 7 = **OUT (0)**.

Bit No.:	IN (1)	OUT (0)	
7	unassigned	unassigned	
6	Permanent simulation of the time status "radio synchronous" even without valid GPS reception	Time status "radio synchronous " only set in case of valid GPS reception	
5	direct synchronisation of the second and the millisecond with the exact GPS second mark (*)	direct synchronisation of the second and the millisecond with the exact GPS second mark only after 2 hours (*)	
4	unassigned	unassigned	
3	unassigned	unassigned	
2	unassigned	unassigned	
1	unassigned	unassigned	
0	unassigned	unassigned	

(*) Explanation referring to the function in system byte Bit-No.: 5:

- Bit-No.: 5 = OUT (0):
 - Crystal operation < 2 hours ⇒

The internal second and millisecond mark are slowly adjusted to the GPS second mark after the GPS resynchronisation (without leap).

- Crystal operation > 2 hours ⇒

The internal second and millisecond mark are directly set to the GPS second mark after the GPS resynchronisation (leap of the internal second mark).

- Bit-No.: 5 = IN (1):
 - Crystal operation ⇒

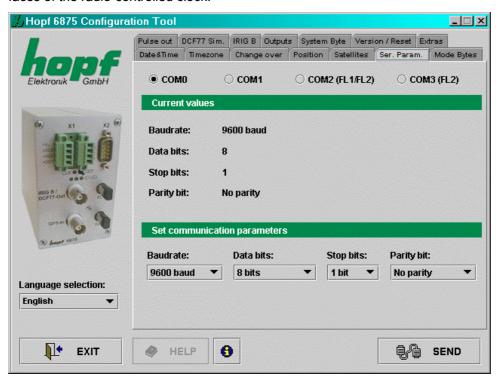
The internal second and millisecond mark are directly set to the GPS second mark after the GPS resynchronisation (leap of the internal second mark).

When "Output in crystal operation is locked" is activated, the signal output of "IMP 1" and "IMP 2" (see chapter optical coupler) will be carried out at the time status "radio synchronous with crystal regulation". Depending on the accuracy demands for the application, the pulse output of the drifting pulses (based on the fluctuant environmental conditions, like e.g. temperature) will be locked or rather disconnected, if the GPS synchronisation fails.



4.3.12 Serial Parameters

This section permits display and modification of the transmission parameters of the serial interfaces of the radio-controlled clock.



The selection of the interface to be configured is made in the upper part of the frame by clicking the appropriate interface [COM0, COM1, COM2 (FL1/FL2) und COM3 (FL2)]. The current values for the selected interface are requested and displayed. These values can be changed by selecting from the lists intended for this purpose.

The following serial parameters may be set:

Baud rate input of the Baud rate: between 150, 300, 600, 1200, 2400, 4800, 9600 and

19200 Baud

Data bits input of the word length: 8 or 7 Bit

Stoppbits number of stop bits: 1 or 2

Parität parity input: no, odd, even

If the serial interface **COM0** of the clock has already been (previously) configured with different parameters (status ex works <9600 baud, 8 data bits, 1 stop bit, no parity>), then the configuration data must be adjusted accordingly so that communication is possible between the configuration software and the clock. The transmission parameters for the serial interface via which the configuration software is configured are stored in the configuration file <**settings.conf**>. This is found in the installation directory (Windows platforms) or in the directory <Installation directory>/etc/ (UNIX-Platforms).

<u>Please Note:</u> By activating the **DEF key** (presss for at least 10 seconds) on the front panel of the clock the serial parameters of the clock are set to

<9600 BAUD, 8 DATA BITS, 1 STOP BIT, NO PARITY>.

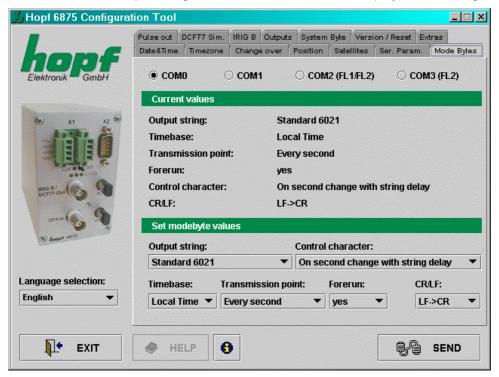


In order to set the transmission parameters for the serial interface in <settings.conf> to the following values <9600 Baud, 8 data bits, 1 stop bit, no parity> the following entries are required:

baudrate=9600 databits=8 stopbits=1 parity=N

4.3.13 Mode bytes

In this section the output strings of the serial interfaces are displayed and changed.



The serial interface to be configured is selected in 4.3.12.

There is a detailed description of the individual data strings in section 5.

The interface(s) designated for the output of the data strings as set must be indicated additionally in section 4.3.15.

Please Note:

THE ENTRIES "C01 CUSTOM STRING" TO "C16 CUSTOM STRING" IN THE SELEC-TION "TRANSMISSION STRING" ARE RESERVED FOR SPECIAL SOLUTIONS AND NOR-MALLY HAVE NO FUNCTION.



The following settings are possible:

Transmission string

Type of data string to be emitted:

Standard 6021,

Standard 6021 with year 2000,

Master/Slave,

Siemens Sinec H1,

T-String, GPS2000

Control character Output of **ETX** control character in the data string:

Standard (direct, no delay),

At the second change (no delay) or At the second change (with delay)

Time basis Time basis for the data string: Local time, UTC

Transmission

time

Output of the data string at the second change:

Each second
Each minute
Each hour
On request

Second forerun Output of the data string with 1 second forerun: no, yes

CR / LF Sequence for CR and LF: CR->LF, LF->CR



4.3.14 Optical coupler

This section enables the configuration of 3 PhotoMOS signal relay outputs and 2 additional pulses. The selection of the signal relay outputs to be configured ("**OK 1**", "**OK 2**" and "**OK 3**") and the pulses ("**IMP 1**" und "**IMP 2**") is made by clicking on the upper part of the frame.



The current values for the selected output or pulse are requested and displayed. Depending on the **"Modus"** which has been set additional methods of configuration will appear or fade. The following modes are supported:

DCF77 (Mode 0)

In this setting the DCF77 pulse will be emitted at the appropriate output. This setting is used, for example, for the synchronization of further DCF77radio-controlled clocks with DCF77 pulse input such as *hopf* 6850. If desired this signal can be inverted. The settings for the DCF77 pulse are in the DCF77 menu and apply to all outputs emitting this.

Sync. Information (Mode 1)

In this setting the internal clock radio-control status is emitted at the corresponding output. If the PhotoMOs signal relay is switched through then the clock is in radio-controlled status. The lapsing of the signals indicates quartz mode. The signal output can not be inverted.

System Information (Mode 2)

In this mode the corresponding output is switched through when the power supply is set. If there is interference the signal lapses and hereby emits an alarm. The signal output cannot be inverted.



Cyclical output: within 24 hours (Mode 3)

In this mode cyclical pulses with an adjustable pulse width can be created on the corresponding output. The following pulse intervals are possible:

every 1, 2, 3, 4, 6, 8, 12 hours every 1, 2, 3, 4, 5, 6, 10, 12, 15, 20, 30 minutes every 1, 2, 3, 4, 5, 6, 10, 12, 15, 20, 30 seconds

The output time of the pulse is fixed by clicking with the mouse on the appropriate arrow filed in the input fields designated for this. A combination of hours, minutes and seconds is not allowed and is prevented by the software.

The pulse length can be selected in the range of **10-2550 msec** in **10 msec** steps. The Pulse length should not exceed the cycle time, because then the output remains constantly switched through.

It is possible to invert the signal output.

Daily pulse (Mode 4)

This mode creates a single pulse per day at the time entered at the output. The output time of the pulse is fixed by clicking on the corresponding fields or by manual entry in the input fields designated for this purpose.

The entries for day, month and year are deactivated.

The pulse length can be selected in the range of 10-2550 msec in 10 msec steps.

It is possible to invert the signal output.

Single pulse (Mode 5)

This mode creates a single pulse per time and date at the output.

This mode creates a single pulse at a defined point in time. The output time of the pulse is fixed by means of a mouse click on the corresponding arrow fields or by manual entry in the fields designated for this.

The pulse length can be selected in the range of **10-2550 msec** in **10 msec** steps. It is possible to invert the signal output.

In the settings *Mode 2* and 3 it is of no benefit to invert the output, since, in the case of power failure, false information would be passed on to the outputs. In the following paragraphs there is an exact description of the individual modes.

By activating the checkbox "Disable output in quartz mode" it is possible, in the *modes 4* and 3, to bind the pulses to the radio-controlled status, specially for **IMP 1** and **IMP 2**. That means that there is only a pulse output when the clock is in radio-controlled mode.

By deactivating the checkbox "Disable output in quartz mode" pulses are emitted in quartz mode.

Configuration for an inverted output of the pulses **IMP 1** and **IMP 2** takes place in the section "Outputs" in 4.3.15.

The settings for the individual PhotoMos signal relays are each transmitted individually to the radio-controlled clock.



4.3.15 Outputs

This section permits the shunting of output signals to the outputs of the radio-controlled clock.



All the settings are made via selection lists.

Only the output of serial data strings is possible via the serial interface **COM0**. This is used mainly for the configuration of the equipment or as a synchronization source.

The outputs: COM0, COM1, COM2 (FL1 / FL2) and COM3 (FL2) are serial interfaces, the output BNC refers to the analogue output IRIG-B / DCF77-Out and TTL describes the digital TTL output on the connector X2.

Methods of configuring **COM1** (serial interface **COM1** in the radio-controlled clock):

- Output signal: data string, IMP1 (pulse1), IMP2 (pulse2), IRIG-B pulse
- Interface: RS232, RS422 full-duplex
- The output signals can also be emitted inversely

Methods of configuring COM2 and COM3 (optical serial interfaces):

- Output signal: data string, IMP1 (pulse1), IMP2 (pulse2), IRIG-B pulse
- The output signals can also be emitted inversely

Methods of configuring BNC:

• Output signal: **DCF77** simulation or **IRIG-B** signal generation

Methods of configuring TTL (digital TTL output in the radio-controlled clock):

- Output signal: data string, IMP1 (pulse1), IMP2 (pulse2), IRIG-B pulse
- The output signals can also be emitted inversely.

<u>Please Note:</u> THE CONFIGURATION OF **IMP1** (PULSE1) AND **IMP2** (PULSE2) IS IN THE "OPTICAL COUPLER" MENU.



4.3.16 DCF77 Simulation

In this section settings can be made for the DCF77 simulation and the DCF77 pulse. These are global settings and are valid for all outputs which emit a DCF77 simulation or DCF77 pulse.



The outputs at which a DCF77 pulse is emitted can be indicated in 4.3.15.

The following entries are required for configuration:

- Pulse length Highbit in the range 140...240 msec (Standard: 200 msec)
- Pulse length Lowbit in the range 70...130 msec (Standard: 100 msec)
- Delay for DCF77 switch-off in the range 2...255 minutes (at 255 ⇒ ∞)
- . Time basis: local time or UTC

The pulse lengths and the switch-off delays are determined by mouse click on the corresponding input fields or by manual entry, the time basis is entered via the selection list.

The value **"DCF77 timeout after"** indicates the delay time in minutes for the output of the DCF77 simulation or the DCF77 pulse when changing to quartz mode. If this value is set at 255 the DCF77 simulation and/or DCF77 pulse will be emitted permanently.



4.3.17 IRIG-B

In this section the settings for the IRIG-B signal generation (analogue) or the IRIG-B pulse are made. These are global settings and are valid for all outputs at which the IRIG-B signal generation or IRIG-B signal pulse is emitted.



The outputs at which an IRIG-B pulse is to be emitted can be indicated in 4.3.15.

The following entries are required for configuration.

- Coding: data format AFNOR (NF S 87-500), IEEE1344
- **Timeout** in range 2..255 minutes (at 255 ⇒ ∞)
- Time basis: local time or UTC

Activating the tick "straight binary seconds" adds the binary day second to the selected data format

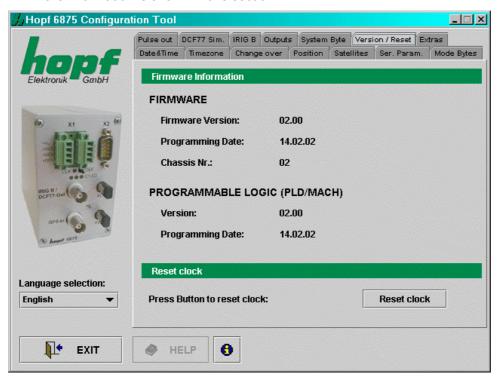
The **"Timeout"** value shows the delay time in minutes for the output of the IRIG-B signal generation (analogue) or the IRIG-B pulse when changing to quartz mode. If the value is set 255 then the IRIG-B signal generation (analogue) or the IRIG-B pulse will be emitted.

Please Note: IRIG-B STANDARD W200-1998 IS A SUBSET OF IEEE1344-1995.



4.3.18 Version / Reset

Firmware information is shown in this section.



Reset clock

A restart of the clock is initiated by this function. The function does not change any of the settings made previously, in contrast to the **DEF** key in the front panel. A reset is necessary after inputs are completed in order to accelerate the first synchronization.

<u>Please Note:</u> When changes have been made on the radio-controlled clock it is advisable to wait for the minute change before setting up reset.



5 Data strings

5.1 General information on the serial data output of the 6875 board

When setting ETX to the second change a transmission gap occurs, depending on the Baud rate, of up to 970 msec. Please pay attention to this when programming timeout on the receiving side.

On all data strings the output of control character CR and LF can be exchanged with **mode-byte**.

The transmitted data string are compatible with the data strings of the following **hopf** clocks:

Board 6020/6021 standard with control character
 Board 7200/7201 standard with control character
 Board 7220/7221 standard with control character
 Board 7240/7245 standard with control character
 Board 6840/6841 standard with control character
 System 4465 standard with control character
 System 6870 standard with control character

5.2 Set-up of the standard (hopf6021) string

character no.:	Meaning	Hex
1	STX (Start of Text)	\$02
2	status (internal status of the clock)	\$30-39, \$41-46
3	day of the week (1=Monday 7=Sunday)	\$31-37
	bit 3 in the day of the week is set to 1 with U	JTC
4	tens hours	\$30-32
5	unit hours	\$30-39
6	tens minutes	\$30-35
7	unit minutes	\$30-39
8	tens seconds	\$30-36
9	unit seconds	\$30-39
10	tens days	\$30-33
11	unit days	\$30-39
12	tens months	\$30-31
13	unit months	\$30-39
14	tens years	\$30-39
15	unit years	\$30-39
16	LF (Line Feed)	\$0A
17	CR (Carriage Return)	\$0D
18	ETX (End of Text)	\$03



5.2.1 Status and day of the week nibble

The second and third ASCII character in the string contain the status and the day of the week. The evaluation of the status is binary. Set-up of the characters:

	b3	b2	b1	b0	Meaning
Status nibble:	х	Х	Х	0	No announcement hour
	х	X	Х	1	Announcement (DST-ST-DST)
	х	X	0	Х	Standard time (ST)
	х	Х	1	Х	Daylight saving time (DST)
	0	0	Х	Х	Time/date invalid
	0	1	Х	Х	Quartz mode
	1	0	Х	Х	Radio-controlled mode
	1	1	х	х	Radio-controlled mode (high accuracy)
Day of the week nibble:	0	Х	Х	Х	CEDST/CET
	1	Х	Х	Х	UTC time
	х	0	0	1	Monday
	х	0	1	0	Tuesday
	х	0	1	1	Wednesday
	х	1	0	0	Thursday
	х	1	0	1	Friday
	х	1	1	0	Saturday
	х	1	1	1	Sunday

Example: (STX)E3123456170496(LF)(CR)(ETX)

Radio-controlled mode (high accuracy)), daylight saving time, no announcement It is Wednesday 17.04.96 - 12:34:56 hrs.

() – ASCII control characters e.g. (STX)

5.2.2 Configuration for NTP (Network Time Protocol)

NTP or also xNTP is a programme package for synchronizing different computer and operating systems with network support. It is the standard for Internet protocol TCP/IP (RFC-1305). Source code and documentation are available as freeware in the Internet under the following address: http://www.ntp.org or <a h

NTP supports the **hopf** protocol as described in section 5.2. The following settings are required in the clock board:

Transmission parameters: 9600 Baud, 8 data bits, no parity, 1 stop bit

Transmission mode: Standard 6021 (hopf6021, time and date), outputevery sec-

ond, time basis: UTC, with second forerun, with ETX at the second change with control characters (STX...ETX), LF->CR $\,$

There are already pre-configured NTP packages for *hopf* radio-controlled clocks with serial interface. On the homepage of Ruprecht&Partner (OEG) (http://www.rdcs.at/) these are available for downloading for the following operating systems:

- RedHat Linux 7.1, SuSE Linux 7.2
- Solaris 8 (SPARC)



5.3 Data string: Standard (hopf6021) with year 2000

The structure of the data string is identical to the standard string. It differs only in the 4-digit transmission of the year.

Current char. no:	<u>Meaning</u>					
1	STX (Start of Text)					
2	status (internal status of clock)					
3	day of the week (1=Monday 7=Sunday)					
	bit 3 in the day of the week is set to 1 with UTC time					
4	tens hours					
5	unit hours					
6	tens minutes					
7	unit minutes					
8	tens seconds					
9	unit seconds					
10	tens days					
11	unit days					
12	tens months					
13	unit months					
14	tens centuries					
15	unit centuries					
16	tens years					
17	unit years					
18	LF (Line Feed)					
19	CR (Carriage Return)					
20	ETX (End of Text)					



5.3.1 Status and day of the week nibble

The second and third ASCII characters in the string contain the status and the day of the week. The evaluation of the status is binary. Set-up of the characters:

	b3	b2	b1	b0	Meaning
Status nibble:	х	Х	Х	0	No announcement hour
	х	Х	Х	1	Announcement (DST-ST-DST)
	х	Х	0	Х	Standard time (ST)
	х	X	1	X	Daylight saving time (DST)
	0	0	X	X	Time/date invalid
	0	1	Х	X	Quartz mode
	1	0	X	X	Radio-controlled mode
	1	1	Х	Х	Radio-controlled mode (high accuracy)
Day of the week nibble:	0	Х	Х	Х	CEDST/CET
	1	Χ	X	X	UTC time
	х	0	0	1	Monday
	х	0	1	0	Tuesday
	х	0	1	1	Wednesday
	х	1	0	0	Thursday
	х	1	0	1	Friday
	х	1	1	0	Saturday
	Х	1	1	1	Sunday

Example: (STX)E312345603011996(LF)(CR)(ETX)

Radio-controlled mode (high accuracy), daylight saving time, no announcement It is Wednesday 03.01.1996 - 12:34:56 hrs.

() – ASCII control characters e.g. (STX)



5.4 Data string SINEC H1

The control characters STX and ETX are only transmitted when the output is set "with control characters". Other wise these control characters do not apply. With the setting "ETX delayed" the last character (ETX) is transmitted at exactly the next second change.

The data string can be accessed with "?" and "T".

Current char. no.:	Meaning	Value (value range)		
1	STX (start of text)	\$02		
2	"D" ASCII D	\$44		
3	":" colon	\$3A		
4	tens days	\$30-33		
5	unit days	\$30-39		
6	"." point	\$2E		
7	tens months	\$30-31		
8	unit months	\$30-39		
9	"." point	\$2E		
10	tens years	\$30-39		
11	unit years	\$30-39		
12	";" semi-colon	\$3B		
13	"T" ASCIIT	\$54		
14	":" colon	\$3A		
15	day of the week	\$31-37		
16	";" semi-colon	\$3B		
17	"U" ASCII U	\$55		
18	":" colon	\$3A		
19	tens hours	\$30-32		
20	unit hours	\$30-39		
21	"." point	\$2E		
22	tens minutes	\$30-35		
23	unit minutes	\$30-39		
24	"." point	\$2E		
25	tens seconds	\$30-36		
26	unit seconds	\$30-39		
27	";" semi-colon	\$3B		
28	"#" or space	\$23 / \$20		
29	"*" or space	\$2A / \$20		
30	"S" or space	\$53 / \$20		
31	"!" or space	\$21 / \$20		
32	ETX (end of text)	\$03		



5.4.1 Status in data string SINEC H1

The characters 28-31 in the data string SINEC H1 provide information about the synchronization status of the clock.

The meanings are as follows::

Character no.: 28 = "#" no radio-controlled synchronization after reset, time invalid

space radio-controlled synchronization after reset, hrs and min in

quartz mode

Character no.: 29 = "*" time from the internal quartz crystal of the clock

space time via radio-controlled reception

Character no.: 30 = "S" "DST" daylight saving time

space "ST" standard time

Character no.: 31 ="!" announcing a changeover from ST/DST or DST/ST

space no announcement

Example: (STX)D:03.01.96;T:1;U:12.34.56; _ _ _ (ETX) (_) = Space

Radio-controlled mode, no announcement, standard time It is Wednesday 03.01.96 - 12:34:56 hrs.



5.5 Data string T-String

The T-string can be transmitted with all modes (e.g. with forerun or final character at the second change).

The data string can be accessed with "T".

Current char. no.:	Meaning	Value (value range)
1	"T" ASCIIT	\$54
2	":" colon	\$3A
3	tens years	\$30-39
4	unit years	\$30-39
5	":" colon	\$3A
6	tens months	\$30-31
7	unit months	\$30-39
8	":" colon	\$3A
9	tens days	\$30-33
10	unit days	\$30-39
11	":" colon	\$3A
12	tens days of the week	\$30
13	unit days of the week	\$31-37
14	":" colon	\$3A
15	tens hours	\$30-32
16	unit hours	\$30-39
17	":" colon	\$3A
18	tens minutes	\$30-35
19	unit minutes	\$30-39
20	":" colon	\$3A
21	tens seconds	\$30-36
22	unit seconds	\$30-39
23	CR (carriage return)	\$0D
24	LF (line feed)	\$0A

Example: T:96:01:03:03:12:34:56(CR)(LF)

It is Wednesday 03.01.96 - 12:34:56 hrs.



5.6 Data string Master/Slave

With master/slave data strings slave systems can be synchronized to an accuracy of \pm 0,5 msec with the time data of the master system. In the data sting the time difference to UTC is also transmitted.

After the year the time difference in hours and minutes is transmitted. The transmission is in BCD. The time difference may be up to \pm 11.59 hrs.

The operational sign appears as the highest bit in the hours.

Logic "1" = local time before UTC Logic "0" = local time after UTC

Example:

90.00	time difference + 10.00 hrs.
01.30	time difference - 01.30 hrs.
81.30	time difference + 01.30 hrs.

The whole data string has the following structure:

Current char. no.:	Meaning	Value (value range)
1	STX (start of text)	\$02
2	status	\$30-39, \$41-46
3	day of week	\$31-37
4	tens hours	\$30-32
5	unit hours	\$30-39
6	tens minutes	\$30-35
7	unit minutes	\$30-39
8	tens seconds	\$30-36
9	unit seconds	\$30-39
10	tens days	\$30-33
11	unit days	\$30-39
12	tens months	\$30-31
13	unit months	\$30-39
14	tens years	\$30-39
15	unit years	\$30-39
16	time diff.10 + symbol	\$30,\$31,\$38,\$39
17	time diff. Unit hrs.	\$30-39
18	time diff. 10 minutes	\$30-35
19	time diff. Unit minutes	\$30-39
20	LF (line feed)	\$0A
21	CR (carriage return)	\$0D
22	ETX (end of text)	\$03



5.6.1 Status in Data String Master/Slave

	b3	b2	b1	b0	Meaning
Status nibble:	х	Х	Х	0	No announcement hour
	х	Х	Х	1	announcement (DST-ST-DST)
	х	Х	0	Х	Standard time (ST)
	х	X	1	Х	Daylight saving time (DST)
	х	0	Х	Х	No announcement switchover second
	х	1	Х	Х	Announcement switchover second
	0	X	Х	Х	Quartz mode
	1	Х	Х	Х	Radio-controlled mode (high accuracy))
Day of the week nibble:	0	0	0	1	Monday
	0	0	1	0	Tuesday
	0	0	1	1	Wednesday
	0	1	0	0	Thursday
	0	1	0	1	Friday
	0	1	1	0	Saturday
	0	1	1	1	Sunday

Example: (STX)831234560301968230(LF)(CR)(ETX)

Radio-controlled mode, no announcement, standard time It is Wednesday 03.01.96 - 12:34:56 hrs.
The time difference to UTC is + 2.30 hrs.

5.6.2 **Setting**

To synchronize the *hopf* slave systems the following settings are required:

- · Output every minute
- · Output second forerun
- · ETX at the second change
- 9600 Baud, 8 bit, 1 stop bit, no parity

With these settings there is optimal control of the time basis in the slave systems.

Please Note: THE OUTPUT OF UTC TIME CAN BE ACTIVATED FOR SPECIAL APPLICATIONS.



5.7 GPS2000 Data String

With the GPS2000 data string systems can be synchronized to an accuracy of \pm 1 µsec with the time data of the master system.

The whole data string has the following structure:

Current char. no.:	Meaning	Value (value range)
1	SOH (start of header)	\$01
2	hundreds day in the year	\$30-33
3	tens day in the year	\$30-39
4	unit day in the year	\$30-39
5	: (colon)	\$3A
6	tens hours	\$30-39
7	unit hours	\$30-36
8	: (colon)	\$3A
9	tens minutes	\$30-33
10	unit minutes	\$30-39
11	: (colon)	\$3A
12	tens seconds	\$30-39
13	unit seconds	\$30-39
14	time accuracy	\$3F, \$23, \$2A, \$2E, \$20
15	CR (carriage return)	\$0D
16	LF (line feed)	\$0A

5.7.1 Time Accuracy in the GPS2000Data String

Hex- value	ASCII- value	Description	Meaning, details of accuracy
\$3F	?	question mark	Error greater than 1 msec
\$23	#	double dagger	Error greater than 100 µsec
\$2A	*	star	Error greater than 10 µsec
\$2E		point	Error greater than 1 µsec
\$20		space	Error greater than 1 µsec

Example: (SOH)042:12:34:56*(CR)(LF)

It is day of the year 42, 12:34:56 hrs., the system time inaccuracy is greater than 10 µsec.



5.7.2 Configuration for GPS2000 Data String

For exact synchronization of the equipment the following settings must are required:

For the first serial interface (e.g. COM0 in 6875)

- 9600 Baud, 8 bit, 1 stop bit, even parity
- · Output every second
- Control characters: standard (direct, without delay)
- Time basis and second forerun as required
- · Transmission time: every second
- CR -> LF

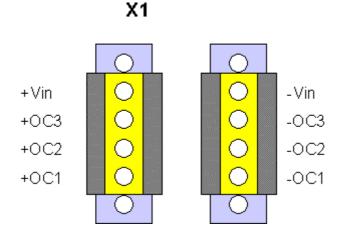
In addition the output of a second pulse is required at the 2nd RS232 serial interface. The pulse width is 10 msec. The falling edge is synchronized to the second mark.

The pulse must be configured separately (e.g. in 6875: IMP1 as cyclical output every second, pulse length 10 msec; emit IMP1 to COM1 as RS232).



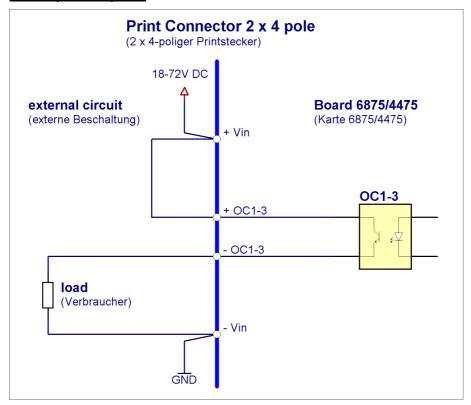
6 Examples of connections

6.1 Assignment of the screw clips



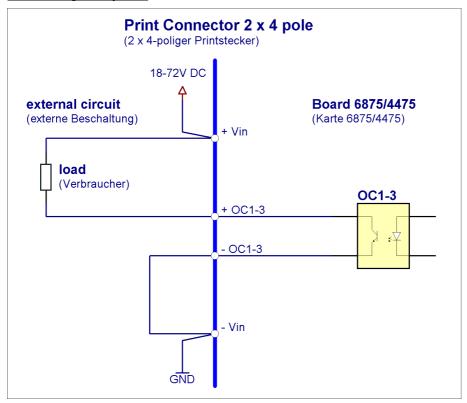
6.1.1 Examples of connections for OC1-3

Active, positive pulse

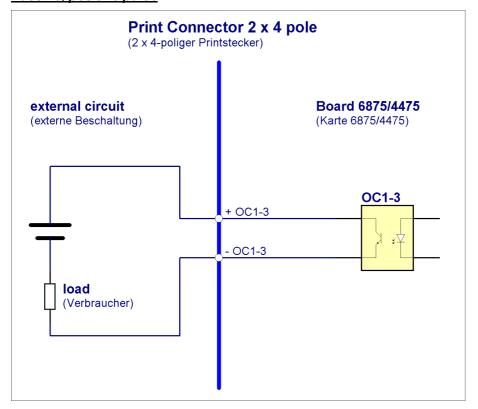




Active, negative pulse

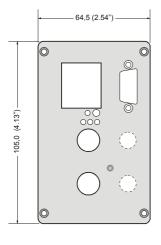


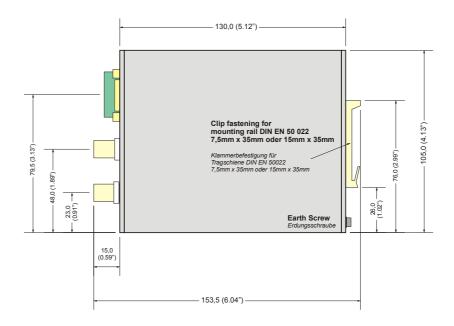
Passive, positive pulse





7 Dimensions of Snap-in Module Housing





8 Glossary und Abbreviations

UTC Universal time coordinated
GPS Global positioning system

DCF77 (D) Deutsches (C) Langwellensignal (F) Frankfurt a.M. (77) Fre-

quenz in kHz German longwave signal Frankfurt a.M. Frequency

in kHz

PPS Pulse Per Second

Standard time — wintertime

DST Daylight Saving Time - *summertime*IRIG-B Inter-Range Instrumentation Group B

AFNOR L'Association Française de Normalisation - Französische Gesell-

schaft für Normung (French Standards Association)

IEEE Institute of Electrical and Electronics Engineers

FL Fiber Optic Link